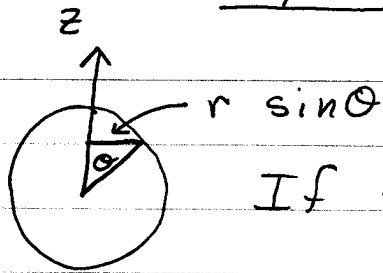


(1)



We first calculate I :

If the density is ρ , the mass is

$$M = \frac{4}{3}\pi R^3 \rho$$

The moment of inertia is

$$I = \int (r \sin \theta)^2 \rho dV$$

$$= \rho \int_0^R dr \int_0^{2\pi} d\phi \int_0^\pi d\theta (r \sin \theta)^2 (r^2 \sin \theta)$$

$$= \rho \underbrace{\int_0^R r^4 dr}_{\frac{R^5}{5}} \underbrace{\int_0^{2\pi} d\phi}_{2\pi} \int_0^\pi \sin^3 \theta d\theta$$

and $\int_0^\pi \sin^3 \theta d\theta = \int_0^\pi (1 - \cos^2 \theta) \sin \theta d\theta$

$$= -\cos \theta \Big|_0^\pi + \int_{+1}^{-1} \cos^2 \theta d(\cos \theta)$$

$$= 2 - \frac{2}{3} = \frac{4}{3}$$

So

$$I = \frac{8\pi}{15} R^5 \rho = \frac{2}{5} MR^2$$

So the angular momentum is $\vec{L} = I \vec{\omega}$
 or $L_z = I \omega$ (assuming rotation about z-axis).

(2) A force is conservative if

$$(\vec{\nabla} \times \vec{F})_x = \partial_y F_z - \partial_z F_y = 0$$

$$(\vec{\nabla} \times \vec{F})_y = \partial_z F_x - \partial_x F_z = 0$$

$$(\vec{\nabla} \times \vec{F})_z = \partial_x F_y - \partial_y F_x = 0$$

(a) If $\vec{F} = (ax, by^2, cz^3)$, each term on the rhs vanishes, so the force is conservative. The potential is found by solving $\vec{F} = -\vec{\nabla}U$:

$$U = -\left(\frac{a}{2}x^2 + \frac{b}{3}y^3 + \frac{c}{4}z^4\right)$$

CK: $\frac{\partial U}{\partial x} = -ax = -F_x$ etc.

(b) $(\vec{\nabla} \times \vec{F})_z = \partial_x F_y = b \neq 0$. Force is not conservative.

(c) $(\vec{\nabla} \times \vec{F})_z = a - a = 0$, $(\vec{\nabla} \times \vec{F})_x = 0$, $(\vec{\nabla} \times \vec{F})_y = 0$

So the force is conservative, and

$$U = -axy$$

since

$$\frac{\partial U}{\partial x} = -ay = -F_x; \quad \frac{\partial U}{\partial y} = -ax = -F_y$$

$$\frac{\partial U}{\partial z} = 0 = -F_z$$

(4.2) (3) $\vec{F} = (x^2, 2xy)$ Compute $W = \int_0^p \vec{F} \cdot d\vec{r}$

(a) $W = \int_0^1 (\vec{F} \cdot \hat{x}) dx + \int_0^1 (\vec{F} \cdot \hat{y}) dy$
 $(y=0) \qquad (x=1)$

$$W = \int_0^1 x^2 dx + \int_0^1 2y dy = \frac{1}{3} + 1 = \boxed{\frac{4}{3}}$$

(b) Path $y = x^2 \Rightarrow dy = 2x dx$

So $W = \int F_x dx + \int F_y dy$

$$= \int_0^1 x^2 dx + \int_0^1 2x \cdot x^2 (2x dx)$$

$$= \int_0^1 (x^2 + 4x^4) dx = \frac{1}{3} + \frac{4}{5} = \boxed{\frac{17}{15}}$$

(c) $x = t^3, y = t^2 \Rightarrow dx = 3t^2 dt, dy = 2t dt$

So $W = \int F_x dx + \int F_y dy$

$$= \int_0^1 t^6 (3t^2 dt) + \int_0^1 2t^3 \cdot t^2 (2t dt)$$

$$= 3 \int_0^1 t^8 dt + 4 \int_0^1 t^6 dt$$

$$= \frac{1}{3} + \frac{4}{7} = \boxed{\frac{19}{21}}$$

Note that since F_x is independent of y , its contribution to W is independent of the path.

(4.8) (4)



Initially the puck is at height $h = 2R$ & $v = 0$. So

$$T = 0, \quad U = mgh = 2mgR$$

The total energy is $E = 2mgR$

At any later time:

$$\frac{1}{2}mv^2 + mgh = 2mgR$$

Since energy is conserved. So $v^2 = 2g(2R - h)$

If the puck is at an angle ϕ from the vertical, the normal force due to gravity is $mg \cos \phi = mg \frac{(h-R)}{R}$.

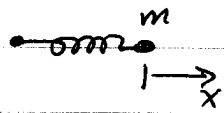
The puck leaves the sphere when this ~~is~~ ^{can no longer provide} the centripetal acceleration v^2/R .

$$\text{Acceleration due to gravity: } g \frac{(h-R)}{R} = \frac{v^2}{R} = \frac{2g(2R-h)}{R}$$

Solve for height:

$$h = \frac{5}{3}R$$

(4.28) (5)



$$U = \frac{1}{2} K x^2$$

$$(a) \quad E = T + U = \frac{1}{2} m v^2 + \frac{1}{2} K x^2$$

$$\text{So } v = \pm \sqrt{\frac{(E - \frac{1}{2} K x^2) 2}{m}}$$

$$\dot{x} = v = \pm \sqrt{\frac{1}{m} (2E - K x^2)} \quad (1)$$

(b) ~~Initially~~, $x = A$ and $v = 0$ at maximum displacement, so $E = \frac{1}{2} K A^2$ then. But it's conserved. Sub into (1):

$$\dot{x} = \pm \sqrt{\frac{K}{m} (A^2 - x^2)}$$

So

$$t = \int_0^x \frac{dx'}{\dot{x}} = \sqrt{\frac{m}{K}} \int_0^x \frac{dx'}{\sqrt{A^2 - x'^2}}$$

Let $x' = A \sin \theta$:

$$t = \sqrt{\frac{m}{K}} \int d\theta = \sqrt{\frac{m}{K}} \theta$$

So

$$t = \sqrt{\frac{m}{K}} \arcsin \frac{x}{A}$$

$$(c) \quad x(t) = A \sin \sqrt{\frac{K}{m}} t$$

So mass executes simple harmonic motion with period $2\pi \sqrt{\frac{m}{K}}$